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Sacherschließung in der wissenschaftlichen Kommunikation neu definiert: Möglichkeiten im Informationszeitalter

Markus Stocker, Irina Sens, Sören Auer



Was wäre wenn ...



- Die globale wissenschaftliche Wissensbasis mehr als ein Dokumentenverzeichnis wäre
- Wissenschaftliche Information und Wissen auch FAIR für Maschinen wäre

Was wäre wenn ...



- Die globale wissenschaftliche Wissensbasis mehr als ein Dokumentenverzeichnis wäre
- Wissenschaftliche Information und Wissen auch FAIR für Maschinen wäre
- Zur Zeit
 - Auffindbarkeit könnte besser sein
 - Angenommen Open Access ist Zugänglichkeit OK
 - Interoperabilität und Nachnutzung ist für Maschinen unmöglich

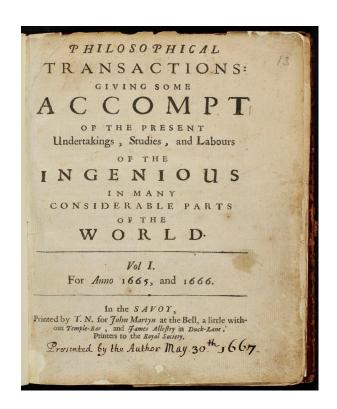
Was wäre wenn ...

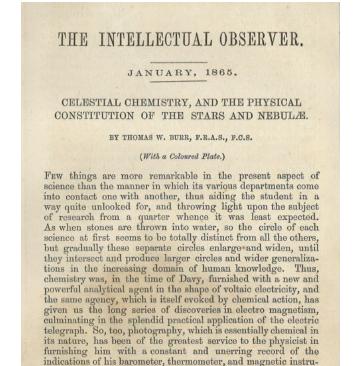


- Die globale wissenschaftliche Wissensbasis mehr als ein Dokumentenverzeichnis wäre
- Wissenschaftliche Information und Wissen auch FAIR für Maschinen wäre
- Zur Zeit
 - Auffindbarkeit könnte besser sein
 - Angenommen Open Access ist Zugänglichkeit OK
 - Interoperabilität und Nachnutzung ist für Maschinen unmöglich
- Die Infrastruktur der wissenschaftlichen Kommunikation steckt im letzten Jahrhundert
- Es gab zwar eine Digitalisierung (engl. digitization) der Dokumente die zuvor gedruckt wurden
- Eine "digitale Revolution" (engl. digitalization) wie in anderen Bereichen ist aber ausgeblieben

Digitalisierung der wissenschaftlichen Kommunikation







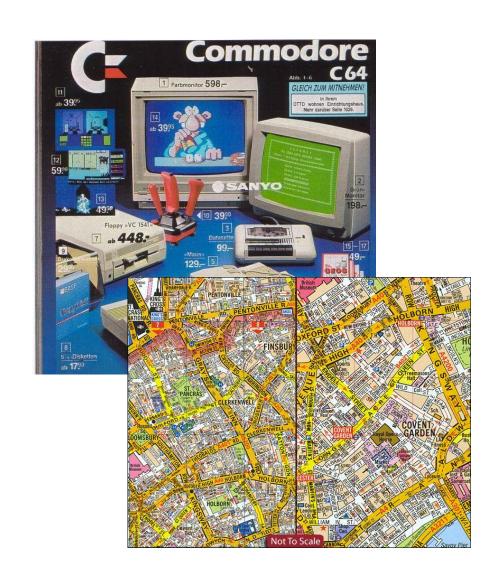


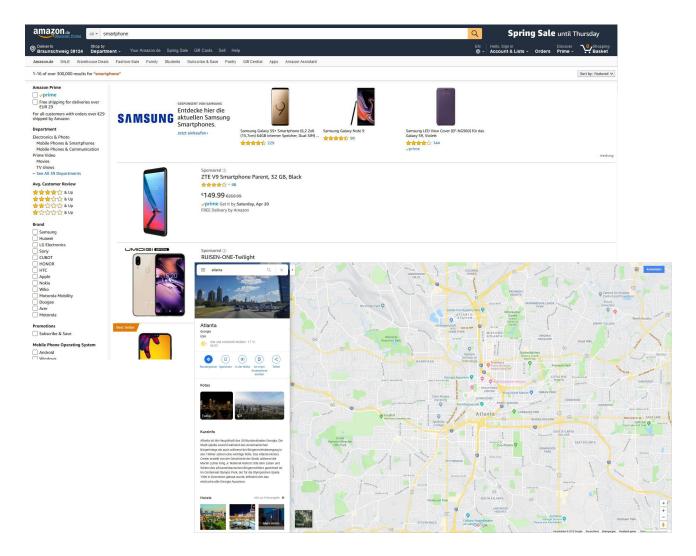
http://doi.org/10.1093/eurhearti/ehw333

... über fast vier Jahrhunderte

Digitalisierung an anderer Stelle

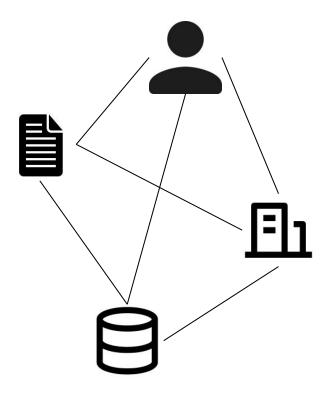






Ganz so schlimm ist es nicht













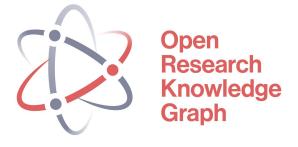




Open Research Knowledge Graph



- Infrastruktur um wissenschaftliches Wissen welches in der Literatur kommuniziert wird maschinenlesbar zu akquirieren, kuratieren, veröffentlichen und prozessieren
- "Tiefe Sacherschließung": Nicht nur bibliographische Metadaten und mehr als Schlagwörter
- Multimodal mit Crowdsourcing, Text Mining, "semantische" Infrastruktur, usw.
- Wenn Wissen generiert wird, Beitrag geschrieben, eingereicht, veröffentlicht, gelesen wird, usw.



Web



http://orkg.org

- Projektseite: https://projects.tib.eu/orkg/
- API Dokumentation: https://www.orkg.org/orkg/doc/api/
- Software: https://gitlab.com/TIBHannover/orkg
- Twitter: https://twitter.com/orkg_org
- Skype: https://join.skype.com/giNqo7JBpvtw
- Mailing list: https://groups.google.com/forum/#!forum/orkg

Scholarly Knowledge. Structured.



IFFE TRANSACTIONS ON INTELLIGENT TRANSPORTATION SYSTEMS, VOL. 15, NO. 4, AUGUST 2014

Situational Knowledge Representation for Traffic Observed by a Pavement Vibration Sensor Network

Markus Stocker, Mauno Rönkkö, and Mikko Kolehmainen

Abstract-Information systems that build on sensor networks of sensors and data [5]-[7], making sense of sensor data is an often process data produced by measuring physical properties. These data can serve in the acquisition of knowledge for real-world situations that are of interest to information services and, ultimately, to people. Such systems face a common challenge, namely the considerable gap between the data produced by measurement and the abstract terminology used to describe real-world situations. We present and discuss the architecture of a software system that utilizes sensor data, digital signal processing, machine learning, and knowledge representation and reasoning to acquire, represent, and infer knowledge about real-world situations observable by a sensor network. We demonstrate the application of the system to vehicle detection and classification by measurement of road pavement vibration. Thus, real-world situations involve vehicles and information for their type, speed, and driving direction.

Index Terms-Knowledge acquisition, knowledge representation, machine learning, sensor data, sensor networks, traffic

I. INTRODUCTION

W E propose a software system architecture and implementation for the continuous and automated representation of knowledge for real-world situations observable by a sensor network. In this paper, we demonstrate the application of signal and to transform sensor data (time domain) into patterns the software system to intelligent transportation systems. Thus, real-world situations involve vehicles and information for their type, speed, and driving direction.

According to Finkelstein [1], "measurement is the process of empirical, objective, assignment of numbers to properties of cepts, instances, and relations. A concept of interest to our them." A sensor is a device that performs measurement, in that represented as instances of this concept. An instance may it transforms the signal of a physical property (e.g., heat) into have a number of relations, e.g., to a spatial location. We numbers or, more generally, into data [2]. Sensor measurement is, hence, the process of recurrent application of such transfor- Network Ontology (SSNO) [14]. SSNO is an "ontology for mation for certain temporal and spatial locations. The result of describing the capabilities of sensors, the act of sensing and the change of the signal over time.

Despite recent advancements in sensor data management, processing, and query [2]-[4], as well as semantic description

Manuscript received April 12, 2013; revised August 16, 2013 and November 20, 2013; accepted December 22, 2013. Date of publication February 4, 2014; date of current version August 1, 2014. The infrastructure o access and collect vibration and camera data, as well as the data, are part of research funded by Tekes, the Finnish Funding Agency for Technology and Innovation (funding decision number 40075/09). The Associate Editor for this paper was P. Grisleri.

The authors are with the Department of Environmental Science, University of Eastern Finland, 70211 Kuopio, Finland (e-mail: markus.stocker@uef.fi;

Digital Object Identifier 10.1109/TTTS.2013.229669

ongoing challenge [8]-[10] because of the difference in the degree to which sensor data represents information about a signal and information about, or related to, a physical property [11]. In other words, it is a challenge because of the considerable gap between data produced by measurement and abstract terminology [12] used by people to describe (the properties of) real-world objects or events.

We are interested in situations involving real-world objects that affect a physical property, for which a signal is measured by means of sensors. In this paper, vehicles are the real-world objects and road pavement vibration is the physical property. We present the architecture of a software system that utilizes digital signal processing, machine learning, and knowledge representation and reasoning to acquire, represent, and infer knowledge about real-world situations involving vehicles. The system aims at reducing the gap between road pavement vibration measurement data and abstract terminology used to describe real-world situations involving vehicles.

Digital signal processing techniques are iteratively applied to a sliding window over sensor data to enhance the vibration (frequency domain). Machine learning is used to classify patterns. We employ multilayer perceptron (MLP) feedforward artificial neural networks [13]. Techniques in knowledge representation are utilized to formally represent domain conobjects or events of the real world in such a way as to describe domain is the vibration sensor. The (installed) sensors are represent sensors and observations using the Semantic Sensor sensor measurement is sensor data. Sensor data represent the resulting observations" [15]. We employ the Situation Theory Ontology2 (STO) [16] to represent knowledge about real-world situations, which are acquired from observations. The STO captures the key aspects of the situation theory developed by Barwise and Perry [17] and extended by Devlin [18]. The theory relates to the work on situation awareness by Endsley [19], [20] as it encompasses most of the concepts discussed in [16]. Both the SSNO and the STO serve as upper ontologies from which we extend to accommodate domain knowledge. The hybrid use of the SSNO and the STO allows for a multilevel abstraction of sensor measurement data and the use of appropriate terminology and formalization at each level.

> http://purl.oclc.org/NET/ssnx/ssn 2http://vistology.com/ont/2008/STO/STO.owl

Search... Sign in View paper Graph view Situational Knowledge Representation for Traffic Observed by a Pavement Vibration Sensor Network Information Science Amarkus Stocker Mauno Rönkkö Mikko Kolehmainen Contributions DOI: 10.1109/TITS.2013.2296697 Classification Knowledge Representation Research problems Add to comparison Road vehicle classification Methods Contribution data **Employs** Machine Learning Utilizes A sensor network **Materials** Training Data Waikato Environment for Knowledge Analysis **Yields** Classification performance for the three sensors (sd1, sd2, Summary of precision and recall figures for the light and Results heavy classes of the vehicle classification task for the three sensors (sd1, sd2, sd3) Summary of the confusion matrices for the vehicle classification task for the three sensors (sd1, sd2, sd3)

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II. MATERIALS AND METHODS

Here, we first present the materials used in this paper, namely the sensor network, the retrieved data, and software. We then detail the methods utilized to process sensor data, as well as to acquire, represent, and infer knowledge.

A. Materials

Road pavement vibration was measured using three CEF C3M01 accelerometer vibration sensors developed by Control Express Finland (CEF) Oy3 for condition monitoring and machinery maintenance. (CEF C3M01 sensors are currently manufactured by Webrosensor Oy⁴ as WBS CM301.) The sensor network was installed at the training site of the Finnish Emergency Services College, Kuopio, Finland. The site is used for emergency response training in simulated situations involving, for instance, vehicles or buildings that are on fire. The area can be accessed by vehicle, and its paved light traveled roads are for different types of vehicles, such as ambulances and fire trucks. The three accelerometer vibration sensors were part of a wider sensor network that consisted of chemical sensors. weather stations, acoustic sensors, and surveillance cameras. The sensor network was installed and maintained for a Finnish research project that aimed at the development of systems for the monitoring of an operational environment.

The accelerometer vibration sensors—hereafter referred to as sensing devices sd₁, sd₂, and sd₃—were installed with a relative distance of approximately 45 m at the right side (with respect to the surveillance camera, described later) along one of the roads at the training site. Each sensor was mounted on a metal bar that penetrated approximately 1 m into the ground, roughly 0.5 m below the paved road surface. The sensors measured ground vibration, including vibration induced by vehicles. We visually monitored the road using an AXIS 211W Wireless Network Camera with an Outdoor Antenna Kit AXIS 211W [21]. The camera was positioned on top of a viewpoint tower located nearby the road and directed toward the monitored road section.



| Research problems | Add to compariso |
|---------------------------|--|
| Road vehicle classificati | on |
| Contribution data | |
| ← Back Mair A sense | or network 🔗 |
| Location | Emergency Services Academy Finland Training Ground |
| Sub system | Accelerometer vibration sensor (sd1) |
| | Accelerometer vibration sensor (sd2) |
| | Accelerometer vibration sensor (sd3) |
| | AXIS 211W Wireless Network Camera |

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The accelerometer vibration sensors—hereafter referred to as sensing devices sd_1 , sd_2 , and sd_3 —were installed with a relative distance of approximately 45 m at the right side (with respect to the surveillance camera, described later) along one of the roads at the training site. Each sensor was mounted on a metal bar that penetrated approximately 1 m into the ground, roughly 0.5 m below the paved road surface. The sensors measured ground vibration, including vibration induced by vehicles. We visually monitored the road using an AXIS 211W Wireless Network Camera with an Outdoor Antenna Kit AXIS 211W [21]. The camera was positioned on top of a viewpoint tower located nearby the road and directed toward the monitored road section.



| Road vehicle classificate Back Mair A set A | ccelerometer vibration sensor (sd1) |
|--|--------------------------------------|
| Datasheet | WBS CM301 Datasheet |
| Manufacturer | Webrosensor Oy |
| Observes | vibration |
| | Accelerometer vibration sensor (sd3) |
| | AXIS 211W Wireless Network Camera |



TABLE III

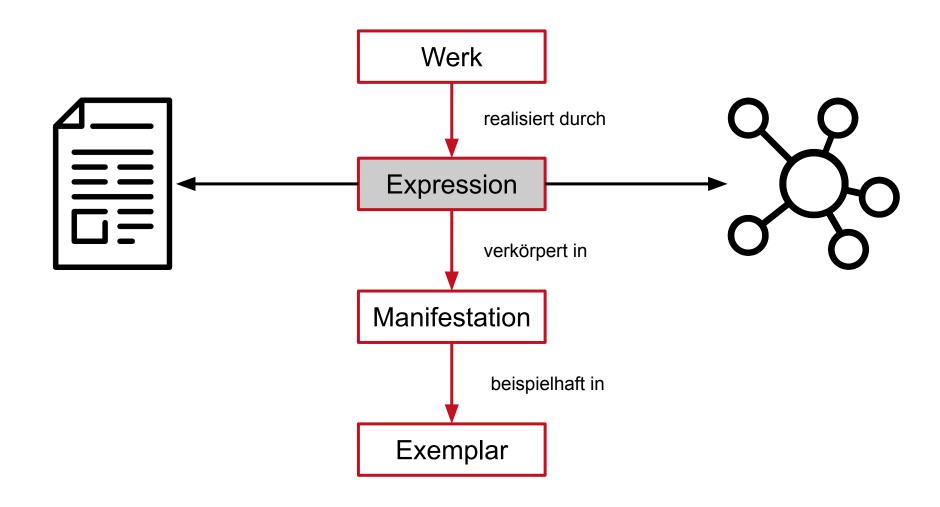
SUMMARY OF PRECISION (P) AND RECALL (R) FIGURES FOR THE CLASSES (C) no-vehicle (NV) AND vehicle (V) OF THE VEHICLE DETECTION (VD) TASK AND THE CLASSES light (L) AND heavy (H) OF THE VEHICLE CLASSIFICATION (VC) TASK FOR THE THREE SENSING DEVICES (SD)

| | С | SD | P | R |
|----|----|--------|-------|-------|
| | | sd_1 | 0.967 | 0.933 |
| | NV | sd_2 | 0.971 | 0.943 |
| VD | | sd_3 | 0.953 | 0.97 |
| VD | | sd_1 | 0.768 | 0.874 |
| | V | sd_2 | 0.928 | 0.963 |
| | | sd_3 | 0.962 | 0.94 |
| | | sd_1 | 0.83 | 0.83 |
| | Н | sdz | 0.721 | 0.778 |
| VC | | sd_3 | 0.842 | 0.774 |
| 1 | | sd_1 | 0.8 | 0.8 |
| | L | sd_2 | 0.788 | 0.732 |
| | | sd_3 | 0.816 | 0.873 |

| Back Mair Sum | Class: heavy; Sensor: sd3 🔗 |
|---------------|-----------------------------|
| Class | heavy |
| Precision | 0.842 |
| Recall | 0.774 |
| Sensor | sd3 |

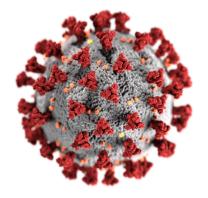
Aus Sicht Functional Requirements for Bibliographic Records







Beispiel COVID-19 Reproduktionszahl



CDC/ Alissa Eckert, MS; Dan Higgins, MAM https://phil.cdc.gov/Details.aspx?pid=23312

arXiv.org > q-bio > arXiv:2003.09320

Search... Help | Advanced Search All fields

Search

Quantitative Biology > Populations and Evolution

COVID-19 e-print

Important: e-prints posted on arXiv are not peer-reviewed by arXiv; they should not be relied upon without context to quide clinical practice or health-related behavior and should not be reported in news media as established information without consulting multiple experts in the field.

[Submitted on 20 Mar 2020]

The early phase of the COVID-19 outbreak in Lombardy, Italy

Cereda D, Tirani M, Rovida F, Demicheli V, Ajelli M, Poletti P, Trentini F, Guzzetta G, Marziano V, Barone A, Magoni M, Deandrea S, Diurno G, Lombardo M, Faccini M, Pan A, Bruno R, Pariani E, Grasselli G, Piatti A, Gramegna M, Baldanti F, Melegaro A, Merler S

In the night of February 20, 2020, the first case of novel coronavirus disease (COVID-19) was confirmed in the Lombardy Region, Italy. In the week that followed, Lombardy experienced a very rapid increase in the number of cases. We analyzed the first 5,830 laboratory-confirmed cases to provide the first epidemiological characterization of a COVID-19 outbreak in a Western Country. Epidemiological data were collected through standardized interviews of confirmed cases and their close contacts. We collected demographic backgrounds, dates of symptom onset, clinical features, respiratory tract specimen results, hospitalization, contact tracing. We provide estimates of the reproduction number and serial interval. The epidemic in Italy started much earlier than February 20, 2020. At the time of detection of the first COVID-19 case, the epidemic had already spread in most municipalities of Southern-Lombardy. The median age for of cases is 69 years (range, 1 month to 101 years). 47% of positive subjects were hospitalized. Among these, 18% required intensive care. The mean serial interval is estimated to be 6.6 days (95% CI, 0.7 to 19). We estimate the basic reproduction number at 3.1 (95% CI, 2.9 to 3.2). We estimated a decreasing trend in the net reproduction number starting around February 20, 2020. We did not observe significantly different viral loads in nasal swabs between symptomatic and asymptomatic. The transmission potential of COVID-19 is very high and the number of critical cases may become largely unsustainable for the healthcare system in a very short-time horizon. We observed a slight decrease of the reproduction number, possibly connected with an increased population awareness and early effect of interventions. Aggressive containment strategies are required to control COVID-19 spread and catastrophic outcomes for the healthcare system.

Subjects: Populations and Evolution (q-bio.PE)

Cite as: arXiv:2003.09320 [q-bio.PE]

(or arXiv:2003.09320v1 [q-bio.PE] for this version)

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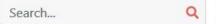


Results

The epidemic in Italy started much earlier than February 20, 2020. At the time of detection of the first COVID-19 case, the epidemic had already spread in most municipalities of Southern-Lombardy. The median age for of cases is 69 years (range, 1 month to 101 years). 47% of positive subjects were hospitalized. Among these, 18% required intensive care. The mean serial interval is estimated to be 6.6 days (95% CI, 0.7 to 19). We estimate the basic reproduction number at 3.1 (95% CI, 2.9 to 3.2). We estimated a decreasing trend in the net reproduction number starting around February 20, 2020. We did not observe significantly different viral loads in nasal swabs between symptomatic and asymptomatic.

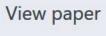
Here we provide an analysis of the first 5,830 laboratory-confirmed cases reported in Lombardy, with date of symptoms onset over the period from January 14 to March 8, 2020. Epidemiological analyses of the confirmed cases and their background demographic and exposure characteristics are presented here as well as the transmission dynamics of the infection within the Region. Also, the virological analysis on a subsample of the reported cases is included to provide preliminary assessment of the level of the viral load among symptomatic and asymptomatic cases.





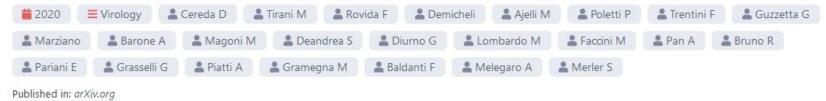








The early phase of the COVID-19 outbreak in Lombardy, Italy



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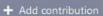
Was wird ermöglicht

2020-01-19/2020-02-26

1.97

1.45-2.48





Contribution comparison

Reproductive number estimates 2019-nCoV

Comparison of the published reproductive number estimates for 2019-nCoV

Reference: 10.1093/jtm/taaa021 🗹

Study date

R0 estimates (average)

95% confidence interval

• Use Shift + Mouse Wheel for horizontal scrolling in the table.

Transmission interval Properties estimates suggest presymptomatic spread of COVID-19 Has research problem COVID-19 reproductive number Singapore

estimates suggest presymptomatic spread of COVID-19 COVID-19 reproductive number Tianjin, China 2020-01-21/2020-02-27 1.87

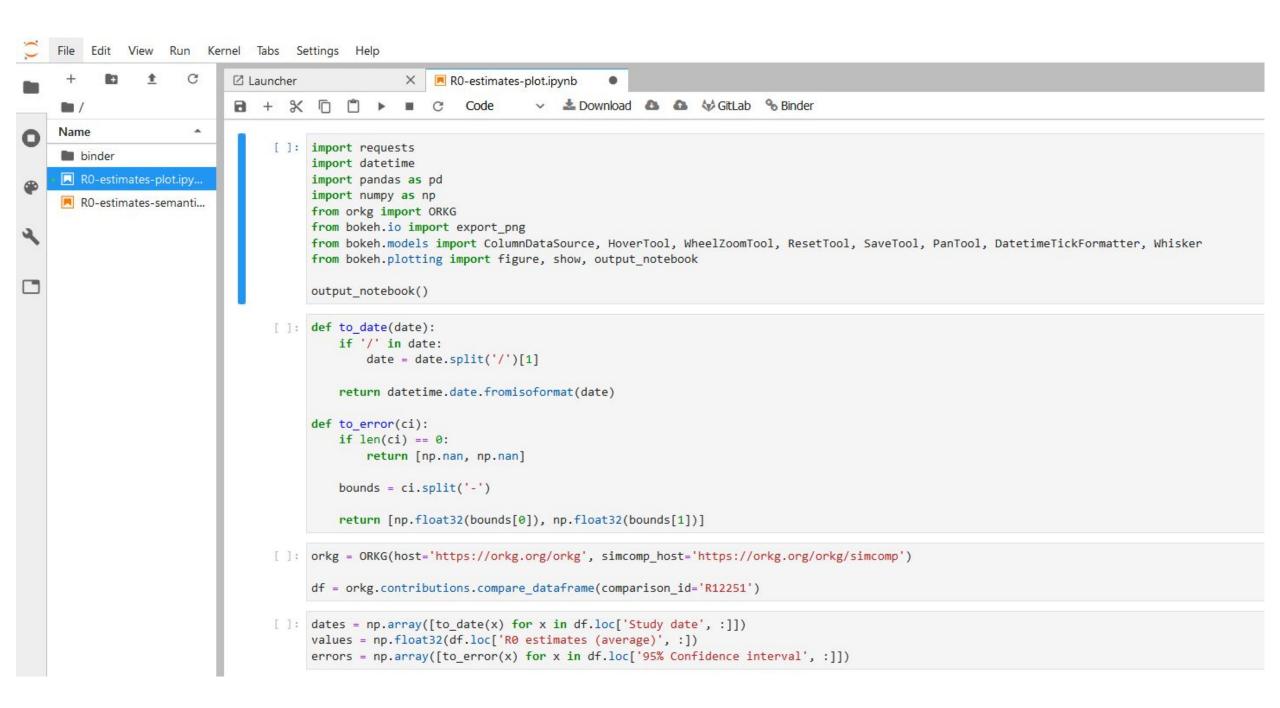
1.65-2.09

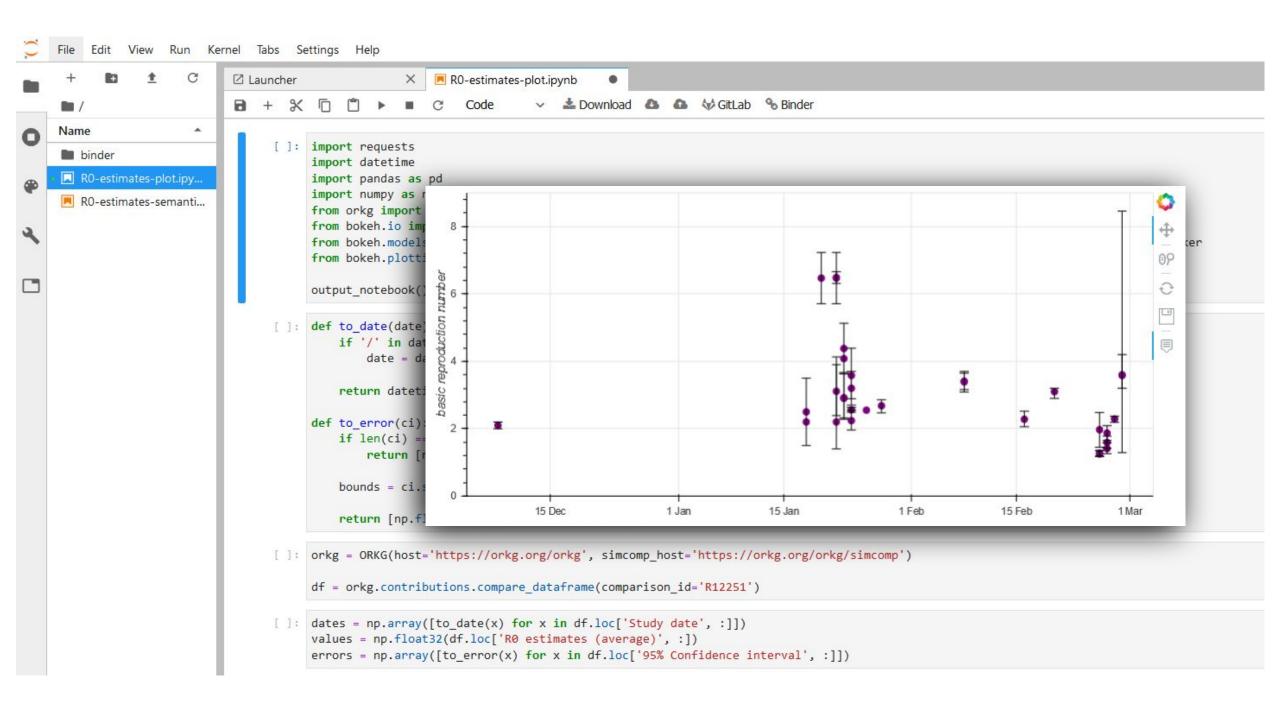
Transmission interval

Estimation of the epidemic properties of the 2019 novel coronavirus: A mathematical modeling study COVID-19 reproductive number Wuhan City, China 2020-01-10/2020-01-23 4.38

3.63-5.13







Schlussbemerkungen



- Ein wissenschaftliches Werk muss nicht zwingend als Artikel realisiert werden
- Man kann Inhalte auch so realisieren, dass diese eher maschinen lesbar sind
- Somit besser verarbeitbar und letztlich FAIRer für Maschinen aber auch Menschen
- Um die erläuterten Ansätze zu skalieren benötigen wir einen "Paradigmenwechsel"